

# DDR3 SDRAM Specification

**204pin Unbuffered SODIMM based on 2Gb B-die  
64-bit Non-ECC**

**78FBGA with Lead-Free & Halogen-Free  
(RoHS compliant)**

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## Revision History

Revision	Month	Year	History
1.0	December	2008	- First Release
1.01	February	2009	- Corrected Module Physical Dimensions.
1.02	February	2009	- Added Tolerances to Physical Dimensions
1.03	June	2009	- Corrected Typo

## 1.0 DDR3 Unbuffered SoDIMM Ordering Information

Part Number	Density	Organization	Component Composition	Number of Rank	Height
M471B5273BH1-CF8/H9	4GB	512Mx64	256Mx8(K4B2G0846B-HC##)*16	2	30mm

Note :

\* ## : F8 / H9

\*\* F8 : 1066Mbps 7-7-7, H9 : 1333Mbps 9-9-9

## 2.0 Key Features

Speed	DDR3-1066	DDR3-1333	Unit
	7-7-7	9-9-9	
tCK(min)	1.875	1.5	ns
CAS Latency	7	9	tCK
tRCD(min)	13.125	13.5	ns
tRP(min)	13.125	13.5	ns
tRAS(min)	37.5	36	ns
tRC(min)	50.625	49.5	ns

- JEDEC standard 1.5V ± 0.075V Power Supply
- $V_{DDQ} = 1.5V \pm 0.075V$
- 400 MHz  $f_{CK}$  for 800Mb/sec/pin, 533MHz  $f_{CK}$  for 1066Mb/sec/pin, 667MHz  $f_{CK}$  for 1333Mb/sec/pin
- 8 independent internal bank
- Programmable CAS Latency: 6,7,8,9
- Programmable Additive Latency(Posted CAS) : 0, CL - 2, or CL - 1 clock
- Programmable CAS Write Latency(CWL) = 5(DDR3-800), 6(DDR3-1066), 7(DDR3-1333)
- 8-bit pre-fetch
- Burst Length: 8 (Interleave without any limit, sequential with starting address "000" only), 4 with tCCD = 4 which does not allow seamless read or write [either On the fly using A12 or MRS]
- Bi-directional Differential Data Strobe
- Internal(self) calibration : Internal self calibration through ZQ pin (RZQ : 240 ohm ± 1%)
- On Die Termination using ODT pin
- Average Refresh Period 7.8us at lower than  $T_{CASE} < 85^{\circ}\text{C}$ , 3.9us at  $85^{\circ}\text{C} < T_{CASE} \leq 95^{\circ}\text{C}$
- Asynchronous Reset

## 3.0 Address Configuration

Organization	Row Address	Column Address	Bank Address	Auto Precharge
256x8(2Gb) based Module	A0-A14	A0-A9	BA0-BA2	A10/AP

## 4.0 x64 DIMM Pin Configurations (Front side/Back Side)

Pin	Front	Pin	Back	Pin	Front	Pin	Back	Pin	Front	Pin	Back
1	V <sub>REFDQ</sub>	2	V <sub>SS</sub>	71	V <sub>SS</sub>	72	V <sub>SS</sub>	139	V <sub>SS</sub>	140	DQ38
3	V <sub>SS</sub>	4	DQ4		KEY			141	DQ34	142	DQ39
5	DQ0	6	DQ5	73	CKE0	74	CKE1	143	DQ35	144	V <sub>SS</sub>
7	DQ1	8	V <sub>SS</sub>	75	V <sub>DD</sub>	76	V <sub>DD</sub>	145	V <sub>SS</sub>	146	DQ44
9	V <sub>SS</sub>	10	<u>DQS0</u>	77	NC	78	A15 <sup>3</sup>	147	DQ40	148	DQ45
11	DM0	12	DQS0	79	BA2	80	A14 <sup>3</sup>	149	DQ41	150	V <sub>SS</sub>
13	V <sub>SS</sub>	14	V <sub>SS</sub>	81	V <sub>DD</sub>	82	V <sub>DD</sub>	151	V <sub>SS</sub>	152	<u>DQS5</u>
15	DQ2	16	DQ6	83	A12/ <u>BC</u>	84	A11	153	DM5	154	DQS5
17	DQ3	18	DQ7	85	A9	86	A7	155	V <sub>SS</sub>	156	V <sub>SS</sub>
19	V <sub>SS</sub>	20	V <sub>SS</sub>	87	V <sub>DD</sub>	88	V <sub>DD</sub>	157	DQ42	158	DQ46
21	DQ8	22	DQ12	89	A8	90	A6	159	DQ43	160	DQ47
23	DQ9	24	DQ13	91	A5	92	A4	161	V <sub>SS</sub>	162	V <sub>SS</sub>
25	V <sub>SS</sub>	26	V <sub>SS</sub>	93	V <sub>DD</sub>	94	V <sub>DD</sub>	163	DQ48	164	DQ52
27	<u>DQS1</u>	28	DM1	95	A3	96	A2	165	DQ49	166	DQ53
29	DQS1	30	<u>RESET</u>	97	A1	98	A0	167	V <sub>SS</sub>	168	V <sub>SS</sub>
31	V <sub>SS</sub>	32	V <sub>SS</sub>	99	V <sub>DD</sub>	100	V <sub>DD</sub>	169	<u>DQS6</u>	170	DM6
33	DQ10	34	DQ14	101	CK0	102	CK1	171	DQS6	172	V <sub>SS</sub>
35	DQ11	36	DQ15	103	<u>CK0</u>	104	<u>CK1</u>	173	V <sub>SS</sub>	174	DQ54
37	V <sub>SS</sub>	38	V <sub>SS</sub>	105	V <sub>DD</sub>	106	V <sub>DD</sub>	175	DQ50	176	DQ55
39	DQ16	40	DQ20	107	A10/AP	108	BA1	177	DQ51	178	V <sub>SS</sub>
41	DQ17	42	DQ21	109	BA0	110	<u>RAS</u>	179	V <sub>SS</sub>	180	DQ60
43	V <sub>SS</sub>	44	V <sub>SS</sub>	111	V <sub>DD</sub>	112	V <sub>DD</sub>	181	DQ56	182	DQ61
45	<u>DQS2</u>	46	DM2	113	<u>WE</u>	114	<u>S0</u>	183	DQ57	184	V <sub>SS</sub>
47	DQS2	48	V <sub>SS</sub>	115	<u>CAS</u>	116	ODT0	185	V <sub>SS</sub>	186	<u>DQS7</u>
49	V <sub>SS</sub>	50	DQ22	117	V <sub>DD</sub>	118	V <sub>DD</sub>	187	DM7	188	DQS7
50	DQ18	52	DQ23	119	A13 <sup>3</sup>	120	ODT1	189	V <sub>SS</sub>	190	V <sub>SS</sub>
53	DQ19	54	V <sub>SS</sub>	121	<u>S1</u>	122	NC	191	DQ58	192	DQ62
55	V <sub>SS</sub>	56	DQ28	123	V <sub>DD</sub>	124	V <sub>DD</sub>	193	DQ59	194	DQ63
57	DQ24	58	DQ29	125	TEST	126	V <sub>REFCA</sub>	195	V <sub>SS</sub>	196	V <sub>SS</sub>
59	DQ25	60	V <sub>SS</sub>	127	V <sub>SS</sub>	128	V <sub>SS</sub>	197	SA0	198	NC
61	V <sub>SS</sub>	62	<u>DQS3</u>	129	DQ32	130	DQ36	199	V <sub>DDSPD</sub>	200	SDA
63	DM3	64	DQS3	131	DQ33	132	DQ37	201	SA1	202	SCL
65	V <sub>SS</sub>	66	V <sub>SS</sub>	133	V <sub>SS</sub>	134	V <sub>SS</sub>	203	V <sub>TT</sub>	204	V <sub>TT</sub>
67	DQ26	68	DQ30	135	<u>DQS4</u>	136	DM4				
69	DQ27	70	DQ31	137	DQS4	138	V <sub>SS</sub>				

Note :

1. NC = No Connect, NU = Not Usable, RFU = Reserved Future Use
2. TEST(pin 125) is reserved for bus analysis probes and is NC on normal memory modules.
3. This address might be connected to NC balls of the DRAMs (depending on density); either way they will be connected to the termination resistor.

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## 5.0 Pin Description

Pin Name	Description	Number	Pin Name	Description	Number
CK0, CK1	Clock Inputs, positive line	2	DQ0-DQ63	Data Input/Output	64
$\overline{\text{CK}0}, \overline{\text{CK}1}$	Clock Inputs, negative line	2	DM0-DM7	Data Masks/ Data strobes, Termination data strobes	8
CKE0, CKE1	Clock Enables	2	DQS0-DQS7	Data strobes	8
$\overline{\text{RAS}}$	Row Address Strobe	1	$\overline{\text{DQS}0}-\overline{\text{DQS}7}$	Data strobes complement	8
$\overline{\text{CAS}}$	Column Address Strobe	1	$\overline{\text{RESET}}$	Reset Pin	1
$\overline{\text{WE}}$	Write Enable	1	TEST	Logic Analyzer specific test pin (No connect on SODIMM)	1
$\overline{\text{S}0}, \overline{\text{S}1}$	Chip Selects	2	V <sub>DD</sub>	Core and I/O Power	18
A0-A9, A11, A13-A15	Address Inputs	14	V <sub>SS</sub>	Ground	52
A10/AP	Address Input/Autoprecharge	1	V <sub>REFDQ</sub> V <sub>REFCA</sub>	Input/Output Reference	2
A12/ $\overline{\text{BC}}$	Address Input/Burst chop	1	V <sub>DDSPD</sub>	SPD and Temp sensor Power	1
BA0-BA2	SDRAM Bank Addresses	3	V <sub>TT</sub>	Termination Voltage	2
ODT0, ODT1	On-die termination control	2	NC	Reserved for future use	3
SCL	Serial Presence Detect (SPD) Clock Input	1		Total	204
SDA	SPD Data Input/Output	1			
SA0-SA1	SPD Address	2			

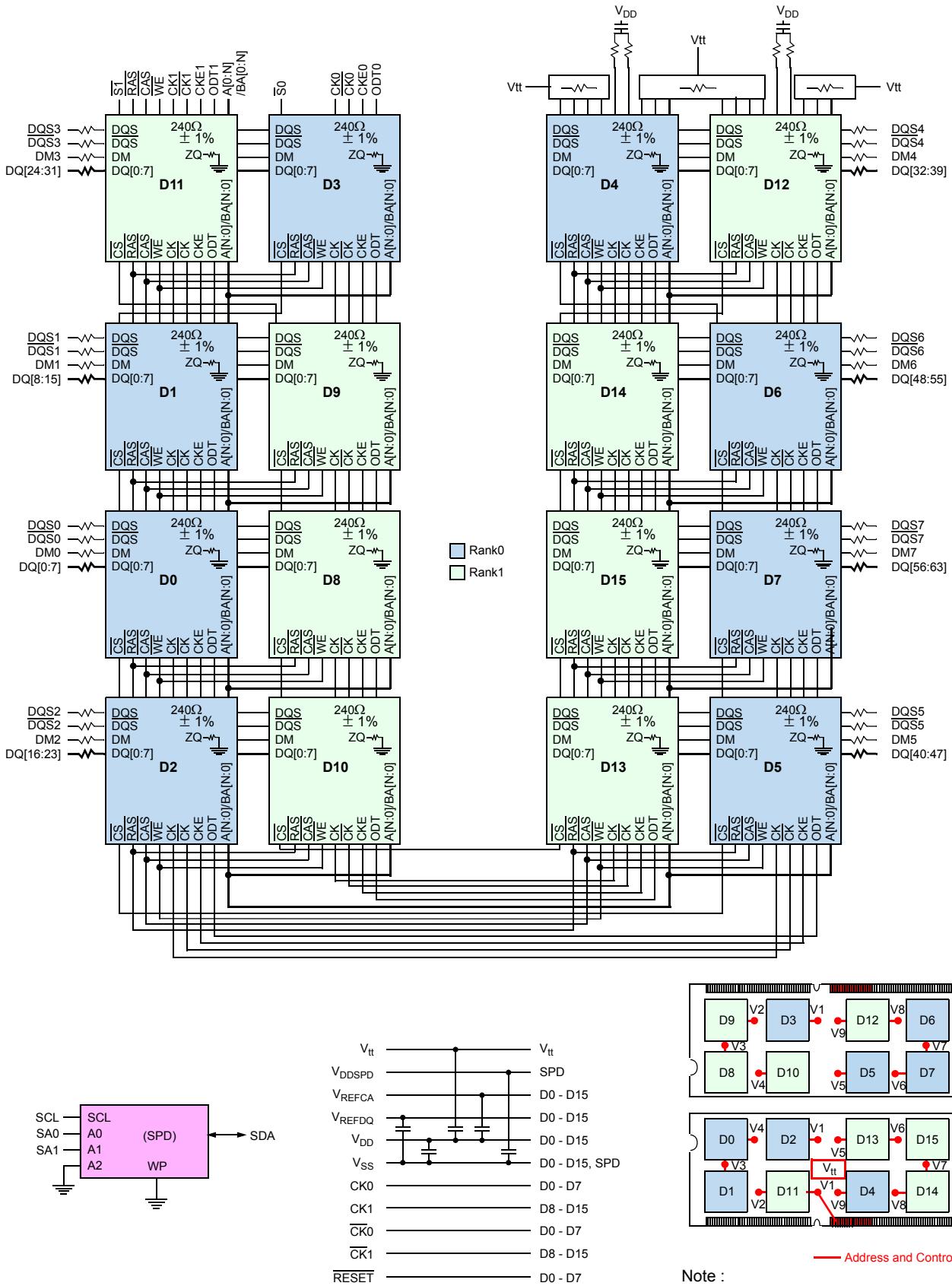
\*The V<sub>DD</sub> and V<sub>DDQ</sub> pins are tied common to a single power-plane on these designs.

## 6.0 Input/Output Functional Description

Symbol	Type	Function
<u>CK0-CK1</u> <u>CK0-CK1</u>	Input	The system clock inputs. All address and command lines are sampled on the cross point of the rising edge of CK and falling edge of CK. A Delay Locked Loop (DLL) circuit is driven from the clock inputs and output timing for read operations is synchronized to the input clock.
CKE0-CKE1	Input	Activates the DDR3 SDRAM CK signal when high and deactivates the CK signal when low. By deactivating the clocks, CKE low initiates the Power Down mode or the Self Refresh mode.
<u>S0-S1</u>	Input	Enables the associated DDR3 SDRAM command decoder when low and disables the command decoder when high. When the command decoder is disabled, new commands are ignored but previous operations continue. Rank 0 is selected by <u>S0</u> ; Rank 1 is selected by <u>S1</u> .
<u>RAS</u> , <u>CAS</u> , <u>WE</u>	Input	When sampled at the cross point of the rising edge of CK and falling edge of <u>CK</u> , signals <u>CAS</u> , <u>RAS</u> , and <u>WE</u> define the operation to be executed by the SDRAM.
BA0-BA2	Input	Selects which DDR3 SDRAM internal bank of eight is activated.
ODT0-ODT1	Input	Asserts on-die termination for DQ, DM, DQS, and DQS signals if enabled via the DDR3 SDRAM mode register.
A0-A9, A10/AP, A11 A12/BC A13-A15	Input	During a Bank Activate command cycle, defines the row address when sampled at the cross point of the rising edge of CK and falling edge of <u>CK</u> . During a Read or Write command cycle, defines the column address when sampled at the cross point of the rising edge of CK and falling edge of <u>CK</u> . In addition to the column address, AP is used to invoke autoprecharge operation at the end of the burst read or write cycle. If AP is high, autoprecharge is selected and BA0-BAn defines the bank to be precharged. If AP is low, autoprecharge is disabled. During a Precharge command cycle, AP is used in conjunction with BA0-BAn to control which bank(s) to precharge. If AP is high, all banks will be precharged regardless of the state of BA0-BAn inputs. If AP is low, then BA0-BAn are used to define which bank to precharge. A12(BC) is sampled during READ and WRITE commands to determine if burst chop (on-the fly) will be performed (HIGH, no burst chop; LOW, burst chopped)
DQ0-DQ63	I/O	Data Input/Output pins.
DM0-DM7	Input	The data write masks, associated with one data byte. In Write mode, DM operates as a byte mask by allowing input data to be written if it is low but blocks the write operation if it is high. In Read mode, DM lines have no effect.
<u>DQS0-DQS7</u> <u>DQS0-DQS7</u>	I/O	The data strobes, associated with one data byte, sourced with data transfers. In Write mode, the data strobe is sourced by the controller and is centered in the data window. In Read mode, the data strobe is sourced by the DDR3 SDRAMs and is sent at the leading edge of the data window. <u>DQS</u> signals are complements, and timing is relative to the crosspoint of respective DQS and <u>DQS</u> .
<u>V<sub>DD</sub></u> , <u>V<sub>DDSPD</sub></u> , <u>V<sub>SS</sub></u>	Supply	Power supplies for core, I/O, Serial Presence Detect, Temp sensor, and ground for the module.
<u>V<sub>REFDQ</sub></u> , <u>V<sub>REFCA</sub></u>	Supply	Reference voltage for SSTL15 inputs.
SDA	I/O	This is a bidirectional pin used to transfer data into or out of the SPD EEPROM and Temp sensor. A resistor must be connected from the SDA bus line to <u>V<sub>DDSPD</sub></u> on the system planar to act as a pull up.
SCL	Input	This signal is used to clock data into and out of the SPD EEPROM and Temp sensor.
SA0-SA1	Input	Address pins used to select the Serial Presence Detect and Temp sensor base address.
TEST	I/O	The TEST pin is reserved for bus analysis tools and is not connected on normal memory modules
RESET	Input	RESET In Active Low This signal resets the DDR3 SDRAM

## 7.0 Function Block Diagram:

7.1 4GB, 512Mx64 Module (Populated as 2 ranks of x8 DDR3 SDRAMs)



**Note :**  
1. DQ wiring may differ from that shown  
however ,DQ, DM, DQS and  $\overline{DQS}$   
relationships are maintained as shown

## 8.0 Absolute Maximum Ratings

### 8.1 Absolute Maximum DC Ratings

Symbol	Parameter	Rating	Units	Notes
$V_{DD}$	Voltage on $V_{DD}$ pin relative to $V_{SS}$	-0.4 V ~ 1.975 V	V	1,3
$V_{DDQ}$	Voltage on $V_{DDQ}$ pin relative to $V_{SS}$	-0.4 V ~ 1.975 V	V	1,3
$V_{IN}, V_{OUT}$	Voltage on any pin relative to $V_{SS}$	-0.4 V ~ 1.975 V	V	1
$T_{STG}$	Storage Temperature	-55 to +100	°C	1, 2

Note :

- Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.
- Storage Temperature is the case surface temperature on the center/top side of the DRAM. For the measurement conditions, please refer to JESD51-2 standard.
- $V_{DD}$  and  $V_{DDQ}$  must be within 300mV of each other at all times; and  $V_{REF}$  must be not greater than  $0.6 \times V_{DDQ}$ . When  $V_{DD}$  and  $V_{DDQ}$  are less than 500mV;  $V_{REF}$  may be equal to or less than 300mV.

### 8.2 DRAM Component Operating Temperature Range

Symbol	Parameter	rating	Unit	Notes
$T_{OPER}$	Operating Temperature Range	0 to 95	°C	1, 2, 3

Note :

- Operating Temperature  $T_{OPER}$  is the case surface temperature on the center/top side of the DRAM. For measurement conditions, please refer to the JEDEC document JESD51-2.
- The Normal Temperature Range specifies the temperatures where all DRAM specifications will be supported. During operation, the DRAM case temperature must be maintained between 0-85°C under all operating conditions
- Some applications require operation of the Extended Temperature Range between 85°C and 95°C case temperature. Full specifications are guaranteed in this range, but the following additional conditions apply:
  - Refresh commands must be doubled in frequency, therefore reducing the refresh interval tREFI to 3.9us. It is also possible to specify a component with 1X refresh (tREFI to 7.8us) in the Extended Temperature Range.
  - If Self-Refresh operation is required in the Extended Temperature Range, then it is mandatory to either use the Manual Self-Refresh mode with Extended Temperature Range capability (MR2 A6 = 0b and MR2 A7 = 1b) or enable the optional Auto Self-Refresh mode (MR2 A6 = 1b and MR2 A7 = 0b)

## 9.0 AC & DC Operating Conditions

### 9.1 Recommended DC Operating Conditions (SSTL-15)

Symbol	Parameter	Rating			Units	Notes
		Min.	Typ.	Max.		
$V_{DD}$	Supply Voltage	1.425	1.5	1.575	V	1,2
$V_{DDQ}$	Supply Voltage for Output	1.425	1.5	1.575	V	1,2

Note :

- Under all conditions  $V_{DDQ}$  must be less than or equal to  $V_{DD}$ .
- $V_{DDQ}$  tracks with  $V_{DD}$ . AC parameters are measured with  $V_{DD}$  and  $V_{DDQ}$  tied together.

## 10.0 AC & DC Input Measurement Levels

### 10.1 AC & DC Logic Input Levels for Single-ended Signals

Single Ended AC and DC input levels for Command and Address

Symbol	Parameter	DDR3-800/1066		DDR3-1333		Unit	Notes
		Min.	Max.	Min.	Max.		
$V_{IH.CA}(DC)$	DC input logic high	$V_{REF} + 100$	$V_{DD}$	$V_{REF} + 100$	$V_{DD}$	mV	1
$V_{IL.CA}(DC)$	DC input logic low	$V_{SS}$	$V_{REF} - 100$	$V_{SS}$	$V_{REF} - 100$	mV	1
$V_{IH.CA}(AC)$	AC input logic high	$V_{REF} + 175$	-	$V_{REF} + 175$	-	mV	1,2
$V_{IL.CA}(AC)$	AC input logic low	-	$V_{REF} - 175$	-	$V_{REF} - 175$	mV	1,2
$V_{IH.CA}(AC150)$	AC input logic high	$V_{REF} + 150$	-	$V_{REF} + 150$	-	mV	1,2
$V_{IL.CA}(AC150)$	AC input logic low	-	$V_{REF} - 150$	-	$V_{REF} - 150$	mV	1,2
$V_{REFCA}(DC)$	Reference Voltage for ADD, CMD inputs	$0.49*V_{DD}$	$0.51*V_{DD}$	$0.49*V_{DD}$	$0.51*V_{DD}$	V	3,4

Note :

1. For input only pins except  $\overline{RESET}$ ,  $V_{REF} = V_{REFCA}(DC)$
2. See "Overshoot and Undershoot specifications" section.
3. The AC peak noise on  $V_{REF}$  may not allow  $V_{REF}$  to deviate from  $V_{REF}(DC)$  by more than  $\pm 1\% V_{DD}$  (for reference : approx.  $\pm 15mV$ )
4. For reference : approx.  $V_{DD}/2 \pm 15mV$

Single Ended AC and DC input levels for DQ and DM

Symbol	Parameter	DDR3-1066		DDR3-1333		Unit	Notes
		Min.	Max.	Min.	Max.		
$V_{IH.DQ}(DC100)$	DC input logic high	$V_{REF} + 100$	$V_{DD}$	$V_{REF} + 100$	$V_{DD}$	mV	1
$V_{IL.DQ}(DC100)$	DC input logic low	$V_{SS}$	$V_{REF} - 100$	$V_{SS}$	$V_{REF} - 100$	mV	1
$V_{IH.DQ}(AC175)$	AC input logic high	$V_{REF} + 175$	-	$V_{REF} + 150$	-	mV	1,2,5
$V_{IL.DQ}(AC175)$	AC input logic low	-	$V_{REF} - 175$	-	$V_{REF} - 150$	mV	1,2,5
$V_{IH.DQ}(AC150)$	AC input logic high	$V_{REF} + 150$	Note	-	-	mV	1,2,5
$V_{IL.DQ}(AC150)$	AC input logic low	Note 2	$V_{REF} - 150$	-	-	mV	1,2,5
$V_{REFDQ}(DC)$	I/O Reference Voltage(DQ)	$0.49*V_{DD}$	$0.51*V_{DD}$	$0.49*V_{DD}$	$0.51*V_{DD}$	V	3,4

Note :

1. For input only pins except  $\overline{RESET}$ ,  $V_{REF} = V_{REFDQ}(DC)$
2. See "Overshoot and Undershoot specifications" section.
3. The AC peak noise on  $V_{REF}$  may not allow  $V_{REF}$  to deviate from  $V_{REF}(DC)$  by more than  $\pm 1\% V_{DD}$  (for reference : approx.  $\pm 15mV$ )
4. For reference : approx.  $V_{DD}/2 \pm 15mV$
5. Single ended swing requirement for  $DQS - \overline{DQS}$  is  $350mV$  (peak to peak). Differential swing requirement for  $DQS - \overline{DQS}$  is  $700mV$  (peak to peak).

## 10.2 V<sub>REF</sub> Tolerances.

The dc-tolerance limits and ac-noise limits for the reference voltages  $V_{REFCA}$  and  $V_{REFDQ}$  are illustrated in Figure 1. It shows a valid reference voltage  $V_{REF}(t)$  as a function of time. ( $V_{REF}$  stands for  $V_{REFCA}$  and  $V_{REFDQ}$  likewise).

$V_{REF}(DC)$  is the linear average of  $V_{REF}(t)$  over a very long period of time (e.g. 1 sec). This average has to meet the min/max requirements of  $V_{REF}$ . Furthermore  $V_{REF}(t)$  may temporarily deviate from  $V_{REF}(DC)$  by no more than  $\pm 1\% V_{DD}$ .

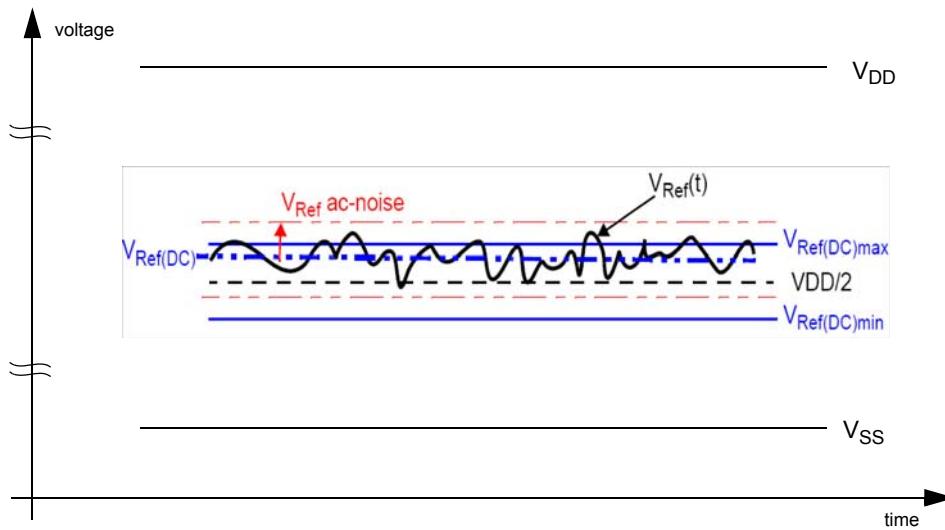


Figure 1. Illustration of  $V_{REF}(DC)$  tolerance and  $V_{REF}$  ac-noise limits

The voltage levels for setup and hold time measurements  $V_{IH}(AC)$ ,  $V_{IH}(DC)$ ,  $V_{IL}(AC)$  and  $V_{IL}(DC)$  are dependent on  $V_{REF}$ .

" $V_{REF}$ " shall be understood as  $V_{REF}(DC)$ , as defined in Figure 1.

This clarifies, that dc-variations of  $V_{REF}$  affect the absolute voltage a signal has to reach to achieve a valid high or low level and therefore the time to which setup and hold is measured. System timing and voltage budgets need to account for  $V_{REF}(DC)$  deviations from the optimum position within the data-eye of the input signals.

This also clarifies that the DRAM setup/hold specification and derating values need to include time and voltage associated with  $V_{REF}$  ac-noise. Timing and voltage effects due to ac-noise on  $V_{REF}$  up to the specified limit ( $\pm 1\% V_{DD}$ ) are included in DRAM timings and their associated deratings.

### 10.3 AC and DC Logic Input Levels for Differential Signals

#### 10.3.1 Differential Signals Definition

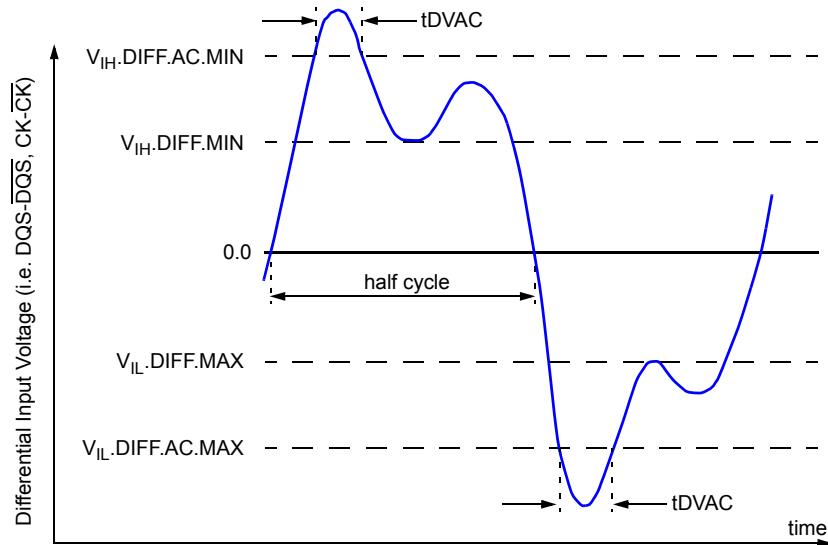


Figure 2. Definition of differential ac-swing and "time above ac level" tDVAC

#### 10.3.2 Differential Swing Requirement for Clock (CK - $\overline{CK}$ ) and Strobe (DQS - $\overline{DQS}$ )

Symbol	Parameter	DDR3-800/1066/1333		unit	Note
		min	max		
$V_{IH\text{diff}}$	differential input high	+0.2	note 3	V	1
$V_{IL\text{diff}}$	differential input low	note 3	-0.2	V	1
$V_{IH\text{diff}}(\text{AC})$	differential input high ac	$2 \times (V_{IH}(\text{AC}) - V_{\text{REF}})$	note 3	V	2
$V_{IL\text{diff}}(\text{AC})$	differential input low ac	note 3	$2 \times (V_{\text{REF}} - V_{IL}(\text{AC}))$	V	2

Notes:

- Used to define a differential signal slew-rate.
- for CK -  $\overline{CK}$  use  $V_{IH}/V_{IL}(\text{AC})$  of ADD/CMD and  $V_{\text{REFCA}}$ ; for DQS -  $\overline{DQS}$ , DQSL -  $\overline{DQSL}$ , DQSU -  $\overline{DQSU}$  use  $V_{IH}/V_{IL}(\text{AC})$  of DQs and  $V_{\text{REFDQ}}$ ; if a reduced ac-high or ac-low level is used for a signal group, then the reduced level applies also here.
- These values are not defined, however they single-ended signals CK,  $\overline{CK}$ , DQS,  $\overline{DQS}$ , DQSL,  $\overline{DQSL}$ , DQSU,  $\overline{DQSU}$  need to be within the respective limits ( $V_{IH}(\text{DC})$  max,  $V_{IL}(\text{DC})$  min) for single-ended signals as well as the limitations for overshoot and undershoot. Refer to "overshoot and Undershoot Specification"

Allowed time before ringback (tDVAC) for CK -  $\overline{CK}$  and DQS -  $\overline{DQS}$ .

Slew Rate [V/ns]	tDVAC [ps] @ $ V_{IH/L\text{diff}}(\text{AC})  = 350\text{mV}$		tDVAC [ps] @ $ V_{IH/L\text{diff}}(\text{AC})  = 300\text{mV}$	
	min	max	min	max
> 4.0	75	-	175	-
4.0	57	-	170	-
3.0	50	-	167	-
2.0	38	-	163	-
1.8	34	-	162	-
1.6	29	-	161	-
1.4	22	-	159	-
1.2	13	-	155	-
1.0	0	-	150	-
< 1.0	0	-	150	-

### 10.3.3 Single-ended Requirements for Differential Signals

Each individual component of a differential signal (CK, DQS, DQSL, DQSU,  $\overline{CK}$ ,  $\overline{DQS}$ ,  $\overline{DQSL}$ , or  $\overline{DQSU}$ ) has also to comply with certain requirements for single-ended signals.

CK and  $\overline{CK}$  have to approximately reach  $V_{SEH\min}$  /  $V_{SEL\max}$  (approximately equal to the ac-levels ( $V_{IH}(AC)$  /  $V_{IL}(AC)$ ) for ADD/CMD signals) in every half-cycle.

DQS, DQSL, DQSU,  $\overline{DQS}$ ,  $\overline{DQSL}$  have to reach  $V_{SEH\min}$  /  $V_{SEL\max}$  (approximately the ac-levels ( $V_{IH}(AC)$  /  $V_{IL}(AC)$ ) for DQ signals) in every half-cycle proceeding and following a valid transition.

Note that the applicable ac-levels for ADD/CMD and DQ's might be different per speed-bin etc. E.g. if  $V_{IH}150(AC)/V_{IL}150(AC)$  is used for ADD/CMD signals, then these ac-levels apply also for the single-ended signals CK and  $\overline{CK}$ .

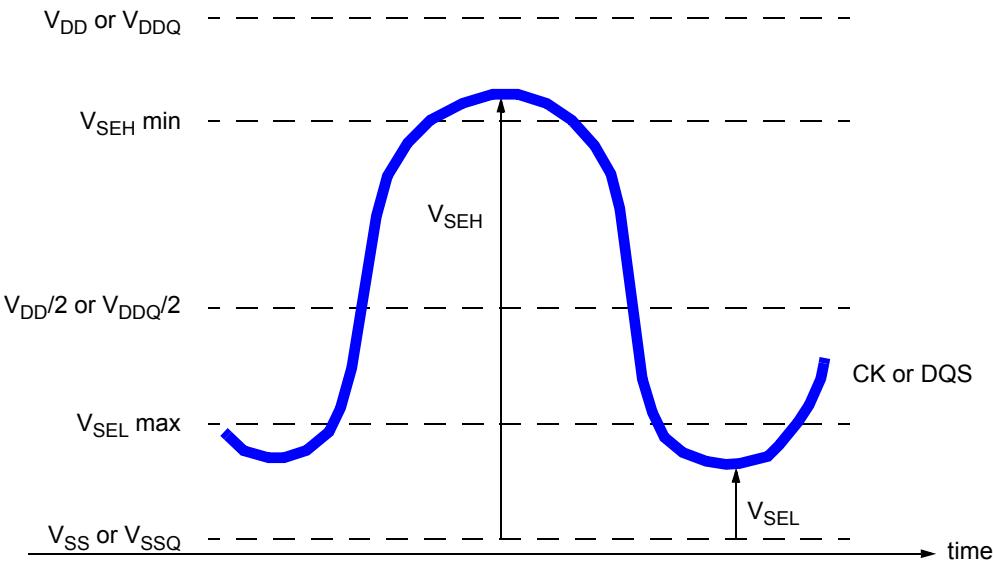


Figure 3. Single-ended requirement for differential signals

Note that while ADD/CMD and DQ signal requirements are with respect to  $V_{REF}$ , the single-ended components of differential signals have a requirement with respect to  $V_{DD}/2$ ; this is nominally the same. The transition of single-ended signals through the ac-levels is used to measure setup time. For single-ended components of differential signals the requirement to reach  $V_{SEL\max}$ ,  $V_{SEH\min}$  has no bearing on timing, but adds a restriction on the common mode characteristics of these signals.

#### Single ended levels for CK, DQS, DQSL, DQSU, $\overline{CK}$ , $\overline{DQS}$ , $\overline{DQSL}$ or $\overline{DQSU}$

Symbol	Parameter	DDR3-800/1066/1333		Unit	Notes
		Min	Max		
$V_{SEH}$	Single-ended high-level for strobes	$(V_{DD}/2)+0.175$	Note3	V	1, 2
	Single-ended high-level for CK, $\overline{CK}$	$(V_{DD}/2)+0.175$	Note3	V	1, 2
$V_{SEL}$	Single-ended low-level for strobes	Note3	$(V_{DD}/2)-0.175$	V	1, 2
	Single-ended low-level for CK, $\overline{CK}$	Note3	$(V_{DD}/2)-0.175$	V	1, 2

Notes:

- For CK,  $\overline{CK}$  use  $V_{IH}/V_{IL}(AC)$  of ADD/CMD; for strobes (DQS,  $\overline{DQS}$ , DQSL,  $\overline{DQSL}$ , DQSU,  $\overline{DQSU}$ ) use  $V_{IH}/V_{IL}(AC)$  of DQs.
- $V_{IH}(AC)/V_{IL}(AC)$  for DQs is based on  $V_{REFDQ}$ ;  $V_{IH}(AC)/V_{IL}(AC)$  for ADD/CMD is based on  $V_{REFCA}$ ; if a reduced ac-high or ac-low level is used for a signal group, then the reduced level applies also here
- These values are not defined, however the single-ended signals CK,  $\overline{CK}$ , DQS,  $\overline{DQS}$ , DQSL,  $\overline{DQSL}$ , DQSU,  $\overline{DQSU}$  need to be within the respective limits ( $V_{IH}(DC)$  max,  $V_{IL}(DC)$ min) for single-ended signals as well as the limitations for overshoot and undershoot. Refer to "Overshoot and Undershoot Specification"

#### 10.3.4 Differential Input Cross Point Voltage

To guarantee tight setup and hold times as well as output skew parameters with respect to clock and strobe, each cross point voltage of differential input signals (CK,  $\overline{CK}$  and DQS,  $\overline{DQS}$ ) must meet the requirements in below table. The differential input cross point voltage  $V_{IX}$  is measured from the actual cross point of true and complement signal to the mid level between of  $V_{DD}$  and  $V_{SS}$ .

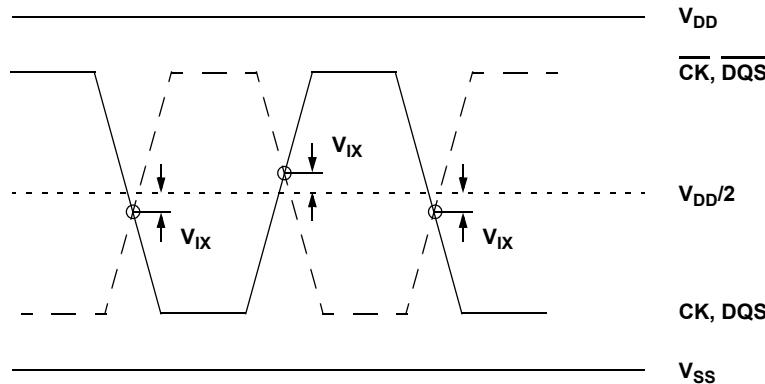


Figure 4.  $V_{IX}$  Definition

#### Cross point voltage for differential input signals (CK, DQS)

Symbol	Parameter	DDR3-800/1066/1333		Unit	Notes
		Min	Max		
$V_{IX}$	Differential Input Cross Point Voltage relative to $V_{DD}/2$ for CK, $\overline{CK}$	-150	150	mV	
		-175	175	mV	1
$V_{IX}$	Differential Input Cross Point Voltage relative to $V_{DD}/2$ for DQS, $\overline{DQS}$	-150	150	mV	

Note :

1. Extended range for  $V_{IX}$  is only allowed for clock and if single-ended clock input signals CK and  $\overline{CK}$  are monotonic, have a single-ended swing  $V_{SEL}$  /  $V_{SEH}$  of at least  $V_{DD}/2 \pm 250$  mV, and the differential slew rate of CK-CK is larger than 3 V/ ns.

#### 10.4 Slew Rate Definition for Single Ended Input Signals

See "Address / Command Setup, Hold and Derating" for single-ended slew rate definitions for address and command signals.

See "Data Setup, Hold and Slew Rate Derating" for single-ended slew rate definitions for data signals.

#### 10.5 Slew rate definition for Differential Input Signals

Input slew rate for differential signals (CK,  $\overline{CK}$  and DQS,  $\overline{DQS}$ ) are defined and measured as shown in below.

##### Differential input slew rate definition

Description	Measured		Defined by
	From	To	
Differential input slew rate for rising edge (CK- $\overline{CK}$ and DQS- $\overline{DQS}$ )	$V_{ILdiffmax}$	$V_{IHdiffmin}$	$\frac{V_{IHdiffmin} - V_{ILdiffmax}}{\Delta TRdiff}$
Differential input slew rate for falling edge (CK- $\overline{CK}$ and DQS- $\overline{DQS}$ )	$V_{IHdiffmin}$	$V_{ILdiffmax}$	$\frac{V_{IHdiffmin} - V_{ILdiffmax}}{\Delta TFdiff}$

Note : The differential signal (i.e. CK -  $\overline{CK}$  and DQS -  $\overline{DQS}$ ) must be linear between these thresholds

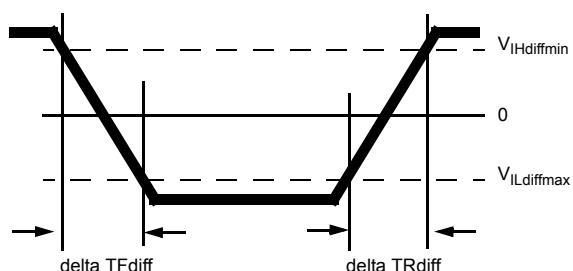


Figure 5. Differential input slew rate definition for DQS,  $\overline{DQS}$  and CK,  $\overline{CK}$

## 11.0 AC & DC Output Measurement Levels

### 11.1 Single Ended AC and DC Output Levels

#### Single Ended AC and DC output levels

Symbol	Parameter	DDR3-800/1066/1333	Units	Notes
$V_{OH}(DC)$	DC output high measurement level (for IV curve linearity)	$0.8 \times V_{DDQ}$	V	
$V_{OM}(DC)$	DC output mid measurement level (for IV curve linearity)	$0.5 \times V_{DDQ}$	V	
$V_{OL}(DC)$	DC output low measurement level (for IV curve linearity)	$0.2 \times V_{DDQ}$	V	
$V_{OH}(AC)$	AC output high measurement level (for output SR)	$V_{TT} + 0.1 \times V_{DDQ}$	V	1
$V_{OL}(AC)$	AC output low measurement level (for output SR)	$V_{TT} - 0.1 \times V_{DDQ}$	V	1

Note : 1. The swing of  $\pm 0.1 \times V_{DDQ}$  is based on approximately 50% of the static single ended output high or low swing with a driver impedance of  $40\Omega$  and an effective test load of  $25\Omega$  to  $V_{TT}=V_{DDQ}/2$ .

### 11.2 Differential AC and DC Output Levels

#### Differential AC and DC output levels

Symbol	Parameter	DDR3-800/1066/1333	Units	Notes
$V_{OHdiff}(AC)$	AC differential output high measurement level (for output SR)	$+0.2 \times V_{DDQ}$	V	1
$V_{OLdiff}(AC)$	AC differential output low measurement level (for output SR)	$-0.2 \times V_{DDQ}$	V	1

Note : 1. The swing of  $\pm 0.2 \times V_{DDQ}$  is based on approximately 50% of the static single ended output high or low swing with a driver impedance of  $40\Omega$  and an effective test load of  $25\Omega$  to  $V_{TT}=V_{DDQ}/2$  at each of the differential outputs.

### 11.3 Single-ended Output Slew Rate

With the reference load for timing measurements, output slew rate for falling and rising edges is defined and measured between  $V_{OL}(AC)$  and  $V_{OH}(AC)$  for single ended signals as shown in below.

#### Single ended Output slew rate definition

Description	Measured		Defined by
	From	To	
Single ended output slew rate for rising edge	$V_{OL}(AC)$	$V_{OH}(AC)$	$\frac{V_{OH}(AC)-V_{OL}(AC)}{\Delta TRse}$
Single ended output slew rate for falling edge	$V_{OH}(AC)$	$V_{OL}(AC)$	$\frac{V_{OH}(AC)-V_{OL}(AC)}{\Delta TFse}$

Note : Output slew rate is verified by design and characterization, and may not be subject to production test.

#### Single ended output slew rate

Parameter	Symbol	DDR3-1066		DDR3-1333		Units
		Min	Max	Min	Max	
Single ended output slew rate	SRQse	2.5	5	2.5	5	V/ns

Description : SR : Slew Rate

Q : Query Output (like in DQ, which stands for Data-in, Query-Output)

se : Singe-ended Signals

For Ron = RZQ/7 setting

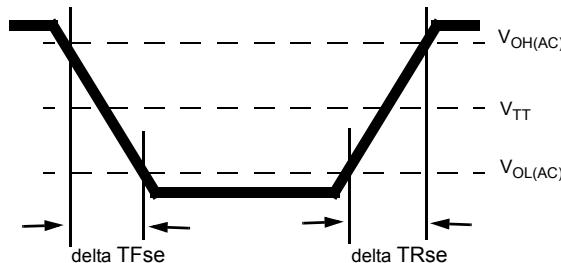


Figure 6. Single-ended output slew rate definition

### 11.4 Differential Output Slew Rate

With the reference load for timing measurements, output slew rate for falling and rising edges is defined and measured between  $V_{OLdiff}(AC)$  and  $V_{OHdiff}(AC)$  for differential signals as shown in below.

#### Differential Output slew rate definition

Description	Measured		Defined by
	From	To	
Differential output slew rate for rising edge	$V_{OLdiff}(AC)$	$V_{OHdiff}(AC)$	$\frac{V_{OHdiff}(AC)-V_{OLdiff}(AC)}{\Delta TRdiff}$
Differential output slew rate for falling edge	$V_{OHdiff}(AC)$	$V_{OLdiff}(AC)$	$\frac{V_{OHdiff}(AC)-V_{OLdiff}(AC)}{\Delta TFdiff}$

Note : Output slew rate is verified by design and characterization, and may not be subject to production test.

#### Differential Output slew rate

Parameter	Symbol	DDR3-1066		DDR3-1333		Units
		Min	Max	Min	Max	
Differential output slew rate	SRQse	5	10	5	10	V/ns

Description : SR : Slew Rate

Q : Query Output (like in DQ, which stands for Data-in, Query-Output

diff : Single-ended Signals

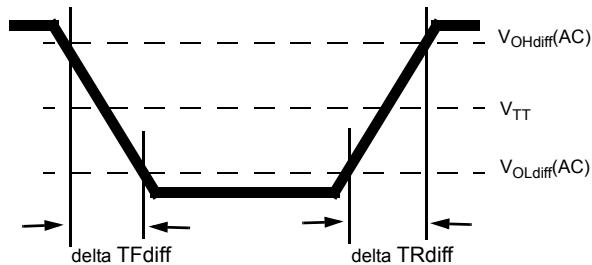


Figure 7. Differential output slew rate definition

## 12.0 IDD specification definition

Symbol	Description
IDD0	<b>Operating One Bank Active-Precharge Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, nRC, nRAS, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> High between ACT and PRE; <b>Command, Address, Bank Address Inputs:</b> partially toggling ; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> Cycling with one bank active at a time: 0,0,1,1,2,2,... ; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
IDD1	<b>Operating One Bank Active-Read-Precharge Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, nRC, nRAS, nRCD, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> High between ACT, RD and PRE; <b>Command, Address, Bank Address Inputs, Data IO:</b> partially toggling ; <b>DM:</b> stable at 0; <b>Bank Activity:</b> Cycling with one bank active at a time: 0,0,1,1,2,2,... ; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0;
IDD2N	<b>Precharge Standby Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> partially toggling ; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks closed; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
DD2NT	<b>Precharge Standby ODT Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> partially toggling ; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks closed; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> toggling
DDQ2NT (optional)	<b>Precharge Standby ODT IDDQ Current</b> Same definition like for IDD2NT, however measuring IDDQ current instead of IDD current
IDD2P0	<b>Precharge Power-Down Current Slow Exit</b> <b>CKE:</b> Low; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> stable at 0; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks closed; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0; <b>Precharge Power Down Mode:</b> Slow Exit <sup>c)</sup>
IDD2P1	<b>Precharge Power-Down Current Fast Exit</b> <b>CKE:</b> Low; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> stable at 0; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks closed; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0; <b>Precharge Power Down Mode:</b> Fast Exit <sup>c)</sup>
IDD2Q	<b>Precharge Quiet Standby Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> stable at 0; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks closed; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
IDD3N	<b>Active Standby Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> partially toggling according to Table 34 ; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks open; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
IDD3P	<b>Active Power-Down Current</b> <b>CKE:</b> Low; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> stable at 1; <b>Command, Address, Bank Address Inputs:</b> stable at 0; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks open; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
IDD4R	<b>Operating Burst Read Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> High between RD; <b>Command, Address, Bank Address Inputs:</b> partially toggling ; <b>Data IO:</b> seamless read data burst with different data between one burst and the next one according to Table 36 ; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks open, <b>RD commands cycling through banks:</b> 0,0,1,1,2,2,... (see Table 7 on page 10); <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
IDDQ4R (optional)	<b>Operating Burst Read IDDQ Current</b> Same definition like for IDD4R, however measuring IDDQ current instead of IDD current
IDD4W	<b>Operating Burst Write Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> High between WR; <b>Command, Address, Bank Address Inputs:</b> partially toggling ; <b>Data IO:</b> seamless write data burst with different data between one burst and the next one ; <b>DM:</b> stable at 0; <b>Bank Activity:</b> all banks open, <b>WR commands cycling through banks:</b> 0,0,1,1,2,2,... ; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at HIGH
IDD5B	<b>Burst Refresh Current</b> <b>CKE:</b> High; <b>External clock:</b> On; <b>tCK, CL, nRFC:</b> AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> High between REF; <b>Command, Address, Bank Address Inputs:</b> partially toggling according to Table 38 ; <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> REF command every nRFC (see Table 38); <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> stable at 0
IDD6	<b>Self Refresh Current: Normal Temperature Range</b> <b>TCASE:</b> 0 - 85°C; <b>Auto Self-Refresh (ASR):</b> Disabled <sup>d)</sup> ; <b>Self-Refresh Temperature Range (SRT):</b> Normal <sup>e)</sup> ; <b>CKE:</b> Low; <b>External clock:</b> Off; <b>CK and CK LOW:</b> CL: AC Timing Table ; <b>BL:</b> 8 <sup>a)</sup> ; <b>AL:</b> 0; <b>CS:</b> Command, Address, Bank Address, <b>Data IO:</b> FLOATING; <b>DM:</b> stable at 0; <b>Bank Activity:</b> Self-Refresh operation; <b>Output Buffer and RTT:</b> Enabled in Mode Registers <sup>b)</sup> ; <b>ODT Signal:</b> FLOATING

Symbol	Description
IDD6ET	<b>Self-Refresh Current: Extended Temperature Range (optional)<sup>f)</sup></b> <b>TCASE: 0 - 95°C; Auto Self-Refresh (ASR): Disabled<sup>d)</sup>; Self-Refresh Temperature Range (SRT): Extended<sup>e)</sup>; CKE: Low; External clock: Off; CK and CK̄: LOW; CL: AC Timing Table ; BL: 8<sup>a)</sup>; AL: 0; CS, Command, Address, Bank Address, Data IO: FLOATING; DM:stable at 0; Bank Activity: Extended Temperature Self-Refresh operation; Output Buffer and RTT: Enabled in Mode Registers<sup>b)</sup>; ODT Signal: FLOATING</b>
IDD6TC	<b>Auto Self-Refresh Current (optional)<sup>f)</sup></b> <b>TCASE: 0 - 95°C; Auto Self-Refresh (ASR): Enabled<sup>d)</sup>, Self-Refresh Temperature Range (SRT): Normal<sup>e)</sup>; CKE: Low; External clock: Off; CK and CK̄: LOW; CL: AC Timing Table ; BL: 8<sup>a)</sup>; AL: 0; CS, Command, Address, Bank Address, Data IO: FLOATING; DM:stable at 0; Bank Activity: Auto Self-Refresh operation; Output Buffer and RTT: Enabled in Mode Registers<sup>b)</sup>; ODT Signal: FLOATING</b>
IDD7	<b>Operating Bank Interleave Read Current</b> <b>CKE: High; External clock: On; tCK, nRC, nRAS, nRCD, nRRD, nFAW, CL: AC Timing Table; BL: 8<sup>a)</sup>; AL: CL-1; CS: High between ACT and RDA; Command, Address, Bank Address Inputs: partially toggling ; Data IO: read data bursts with different data between one burst and the next one ; DM:stable at 0; Bank Activity: two times interleaved cycling through banks (0, 1, ...7) with different addressing, see Table 39 ; Output Buffer and RTT: Enabled in Mode Registers<sup>b)</sup>; ODT Signal: stable at 0</b>

a) Burst Length: BL8 fixed by MRS: set MR0 A[1,0]=00B

b) Output Buffer Enable: set MR1 A[12] = 0B; set MR1 A[5,1] = 01B; RTT\_Nom enable: set MR1 A[9,6,2] = 011B; RTT\_Wr enable: set MR2 A[10,9] = 10B

c) Precharge Power Down Mode: set MR0 A12=0B for Slow Exit or MR0 A12=1B for Fast Exit

d) Auto Self-Refresh (ASR): set MR2 A6 = 0B to disable or 1B to enable feature

e) Self-Refresh Temperature Range (SRT): set MR2 A7=0B for normal or 1B for extended temperature range

f) Refer to DRAM supplier data sheet and/or DIMM SPD to determine if optional features or requirements are supported by DDR3 SDRAM device

g) IDD current measure method and detail patterns are described on DDR3 component datasheet

## 12.1 IDD SPEC Table

## M471B5273BH1 : 4GB (512Mx64) Module

Symbol	CF8 (DDR3-1066@CL=7)	CH9 (DDR3-1333@CL=9)	Unit	Notes
IDD0	880	920	mA	
IDD1	1000	1040	mA	
IDD2P0(slow exit)	192	192	mA	
IDD2P1(fast exit)	480	560	mA	
IDD2N	640	640	mA	
IDD2Q	560	640	mA	
IDD3P(fast exit)	560	560	mA	
IDD3N	760	800	mA	
IDD4R	1320	1480	mA	
IDD4W	1360	1520	mA	
IDD5B	1800	1800	mA	
IDD6	192	192	mA	
IDD7	2160	2560	mA	

## 13.0 Input/Output Capacitance

## 13.1 2Rx16 1GB SoDIMM

Parameter	Symbol	M471B5273BH1				Units	Notes		
		DDR3-1066		DDR3-1333					
		Min	Max	Min	Max				
Input/output capacitance (DQ, DM, DQS, $\overline{DQS}$ , TDQS, $\overline{TDQS}$ )	CIO	-	TBD	-	TBD	pF			
Input capacitance (CK and $\overline{CK}$ )	CCK	-	TBD	-	TBD	pF			
Input capacitance (All other input-only pins)	CI	-	TBD	-	TBD	pF			
Input/output capacitance of ZQ pin	CZQ	-	TBD	-	TBD	pF			

## 14.0 Electrical Characteristics and AC timing

(0 °C < T<sub>CASE</sub> ≤ 95 °C, V<sub>DDQ</sub> = 1.5V ± 0.075V; V<sub>DD</sub> = 1.5V ± 0.075V)

### 14.1 Refresh Parameters by Device Density

Parameter	Symbol	1Gb	2Gb	4Gb	8Gb	Units	Note
All Bank Refresh to active/refresh cmd time	tRFC	110	160	300	350	ns	
Average periodic refresh interval	tREFI	0 °C ≤ T <sub>CASE</sub> ≤ 85°C	7.8	7.8	7.8	μs	
		85 °C < T <sub>CASE</sub> ≤ 95°C	3.9	3.9	3.9	μs	1

Note :

1. Users should refer to the DRAM supplier data sheet and/or the DIMM SPD to determine if DDR3 SDRAM devices support the following options or requirements referred to in this material.

### 14.2 Speed Bins and CL, tRCD, tRP, tRC and tRAS for Corresponding Bin

Speed	DDR3-1066	DDR3-1333	Units	Note
Bin (CL - tRCD - tRP)	7-7-7	9-9-9		
Parameter	min	min		
CL	7	9	tCK	
tRCD	13.13	13.5	ns	
tRP	13.13	13.5	ns	
tRAS	37.5	36	ns	
tRC	50.63	49.5	ns	
tRRD	7.5	6.0	ns	
tFAW	37.5	30	ns	

## 14.3 Speed Bins and CL, tRCD, tRP, tRC and tRAS for corresponding Bin

DDR3 SDRAM Speed Bins include tCK, tRCD, tRP, tRC and tRAS for each corresponding bin.

## DDR3-1066 Speed Bins

Speed		DDR3-1066		Units	Note
CL-nRCD-nRP		7 - 7 - 7			
Parameter	Symbol	min	max		
Internal read command to first data	tAA	13.125	20	ns	
ACT to internal read or write delay time	tRCD	13.125	-	ns	
PRE command period	tRP	13.125	-	ns	
ACT to ACT or REF command period	tRC	50.625	-	ns	
ACT to PRE command period	tRAS	37.5	9*tREFI	ns	8
CL = 6	CWL = 5	tCK(AVG)	2.5	3.3	ns 1,2,3,6
	CWL = 6	tCK(AVG)	Reserved		ns 1,2,3,4
CL = 7	CWL = 5	tCK(AVG)	Reserved		ns 4
	CWL = 6	tCK(AVG)	1.875	<2.5	ns 1,2,3,4
CL = 8	CWL = 5	tCK(AVG)	Reserved		ns 4
	CWL = 6	tCK(AVG)	1.875	<2.5	ns 1,2,3
Supported CL Settings		6,7,8		nCK	
Supported CWL Settings		5,6		nCK	

## DDR3-1333 Speed Bins

Speed		DDR3-1333		Units	Note	
CL-nRCD-nRP		9 - 9 - 9				
Parameter	Symbol	min	max			
Internal read command to first data	tAA	13.5 (13.125) <sup>5,9</sup>	20	ns		
ACT to internal read or write delay time	tRCD	13.5 (13.125) <sup>5,9</sup>	-	ns		
PRE command period	tRP	13.5 (13.125) <sup>5,9</sup>	-	ns		
ACT to ACT or REF command period	tRC	49.5 (49.125) <sup>5,9</sup>	-	ns		
ACT to PRE command period	tRAS	36	9*tREFI	ns	8	
CL = 6	CWL = 5	tCK(AVG)	2.5	3.3	ns 1,2,3,7	
	CWL = 6	tCK(AVG)	Reserved		ns 1,2,3,4,7	
	CWL = 7	tCK(AVG)	Reserved		ns 4	
CL = 7	CWL = 5	tCK(AVG)	Reserved		ns 4	
	CWL = 6	tCK(AVG)	1.875	<2.5	ns 1,2,3,4,7	
			(Optional) Note 5,9			
	CWL = 7	tCK(AVG)	Reserved		ns 1,2,3,4,	
CL = 8	CWL = 5	tCK(AVG)	Reserved		ns 4	
	CWL = 6	tCK(AVG)	1.875	<2.5	ns 1,2,3,7	
	CWL = 7	tCK(AVG)	Reserved		ns 1,2,3,4,	
CL = 9	CWL = 5,6	tCK(AVG)	Reserved		ns 4	
	CWL = 7	tCK(AVG)	1.5	<1.875	ns 1,2,3,4	
CL = 10	CWL = 5,6	tCK(AVG)	Reserved		ns 4	
	CWL = 7	tCK(AVG)	1.5	<1.875	ns 1,2,3	
			(Optional)		ns 5	
Supported CL Settings		6,7,8,9		nCK		
Supported CWL Settings		5,6,7		nCK		

## 14.3.1 Speed Bin Table Notes

Absolute Specification ( $T_{OPER}$ ;  $V_{DDQ} = V_{DD} = 1.5V \pm 0.075 V$ );

Note :

1. The CL setting and CWL setting result in tCK(AVG).MIN and tCK(AVG).MAX requirements. When making a selection of tCK(AVG), both need to be fulfilled: Requirements from CL setting as well as requirements from CWL setting.
2. tCK(AVG).MIN limits: Since CAS Latency is not purely analog - data and strobe output are synchronized by the DLL - all possible intermediate frequencies may not be guaranteed. An application should use the next smaller JEDEC standard tCK(AVG) value (2.5, 1.875, 1.5, or 1.25 ns) when calculating  $CL [nCK] = tAA [ns] / tCK(AVG) [ns]$ , rounding up to the next "SupportedCL".
3. tCK(AVG).MAX limits: Calculate  $tCK(AVG) = tAA.MAX / CL SELECTED$  and round the resulting tCK(AVG) down to the next valid speed bin (i.e. 3.3ns or 2.5ns or 1.875 ns or 1.25 ns). This result is tCK(AVG).MAX corresponding to CL SELECTED.
4. "Reserved" settings are not allowed. User must program a different value.
5. "Optional" settings allow certain devices in the industry to support this setting, however, it is not a mandatory feature. Refer to supplier's data sheet and/or the DIMM SPD information if and how this setting is supported.
6. Any DDR3-1066 speed bin also supports functional operation at lower frequencies as shown in the table which are not subject to Production Tests but verified by Design/Characterization.
7. Any DDR3-1333 speed bin also supports functional operation at lower frequencies as shown in the table which are not subject to Production Tests but verified by Design/Characterization.
8. Any DDR3-1600 speed bin also supports functional operation at lower frequencies as shown in the table which are not subject to Production Tests but verified by Design/Characterization.
9. For devices supporting optional downshift to CL=7 and CL=9, tAA/tRCD/tRP min must be 13.125 ns or lower. SPD settings must be programmed to match. For example, DDR3-1333(CL9) devices supporting downshift to DDR3-1066(CL7) should program 13.125 ns in SPD bytes for tAAmin (Byte 16), tRCDmin (Byte 18), and tRPmin (Byte 20). DDR3-1600(CL11) devices supporting downshift to DDR3-1333(CL9) or DDR3-1066(CL7) should program 13.125 ns in SPD bytes for tAAmin (Byte16), tRCDmin (Byte 18), and tRPmin (Byte 20). Once tRP (Byte 20) is programmed to 13.125ns, tRCmin (Byte 21,23) also should be programmed accordingly. For example, 49.125ns (tRASmin + tRPmin=36ns+13.125ns) for DDR3-1333(CL9) and 48.125ns (tRASmin+tRPmin=35ns+13.125ns) for DDR3-1600(CL11).

## 15.0 Timing Parameters for DDR3-1066 and DDR3-1333

## Timing Parameters by Speed Bin

Speed		DDR3-1066		DDR3-1333		Units	Note
Parameter	Symbol	MIN	MAX	MIN	MAX		
<b>Clock Timing</b>							
Minimum Clock Cycle Time (DLL off mode)	tCK(DLL_OF_F)	8	-	8	-	ns	6
Average Clock Period	tCK(avg)	See Speed Bins Table				ps	
Clock Period	tCK(abs)	tCK(avg)min + tJIT(per)min	tCK(avg)max + tJIT(per)max	tCK(avg)min + tJIT(per)min	tCK(avg)max + tJIT(per)max	ps	
Average high pulse width	tCH(avg)	0.47	0.53	0.47	0.53	tCK(avg)	
Average low pulse width	tCL(avg)	0.47	0.53	0.47	0.53	tCK(avg)	
Clock Period Jitter	tJIT(per)	-90	90	-80	80	ps	
Clock Period Jitter during DLL locking period	tJIT(per, lck)	-80	80	-70	70	ps	
Cycle to Cycle Period Jitter	tJIT(cc)	180		160		ps	
Cycle to Cycle Period Jitter during DLL locking period	tJIT(cc, lck)	160		140		ps	
Cumulative error across 2 cycles	tERR(2per)	-132	132	-118	118	ps	
Cumulative error across 3 cycles	tERR(3per)	-157	157	-140	140	ps	
Cumulative error across 4 cycles	tERR(4per)	-175	175	-155	155	ps	
Cumulative error across 5 cycles	tERR(5per)	-188	188	-168	168	ps	
Cumulative error across 6 cycles	tERR(6per)	-200	200	-177	177	ps	
Cumulative error across 7 cycles	tERR(7per)	-209	209	-186	186	ps	
Cumulative error across 8 cycles	tERR(8per)	-217	217	-193	193	ps	
Cumulative error across 9 cycles	tERR(9per)	-224	224	-200	200	ps	
Cumulative error across 10 cycles	tERR(10per)	-231	231	-205	205	ps	
Cumulative error across 11 cycles	tERR(11per)	-237	237	-210	210	ps	
Cumulative error across 12 cycles	tERR(12per)	-242	242	-215	215	ps	
Cumulative error across n = 13, 14 ... 49, 50 cycles	tERR(nper)	tERR(nper)min = (1 + 0.68ln(n))*tJIT(per)/min tERR(nper)max = (1 - 0.68ln(n))*tJIT(per)/max				ps	24
Absolute clock HIGH pulse width	tCH(abs)	0.43	-	0.43	-	tCK(avg)	25
Absolute clock Low pulse width	tCL(abs)	0.43	-	0.43	-	tCK(avg)	26
<b>Data Timing</b>							
DQS, DQS to DQ skew, per group, per access	tDQSQ	-	150	-	125	ps	13
DQ output hold time from DQS, DQS	tQH	0.38	-	0.38	-	tCK(avg)	13, g
DQ low-impedance time from CK, CK	tLZ(DQ)	-600	300	-500	250	ps	13,14, f
DQ high-impedance time from CK, CK	tHZ(DQ)	-	300	-	250	ps	13,14, f
Data setup time to DQS, DQS referenced to V <sub>IH</sub> (AC)V <sub>IL</sub> (AC) levels	tDS(base)	25	-	30	-	ps	d, 17
Data hold time to DQS, DQS referenced to V <sub>IH</sub> (AC)V <sub>IL</sub> (AC) levels	tDH(base)	100	-	65	-	ps	d, 17
DQ and DM Input pulse width for each input	tDIPW	490	-	400	-	ps	28
<b>Data Strobe Timing</b>							
DQS, DQS READ Preamble	tRPRE	0.9	Note 19	0.9	Note 19	tCK	13, 19, g
DQS, DQS differential READ Postamble	tRPST	0.3	Note 11	0.3	Note 11	tCK	11, 13, b
DQS, DQS output high time	tQSH	0.38	-	0.4	-	tCK(avg)	13, g
DQS, DQS output low time	tQL	0.38	-	0.4	-	tCK(avg)	13, g
DQS, DQS WRITE Preamble	tWPRE	0.9	-	0.9	-	tCK	
DQS, DQS WRITE Postamble	tWPST	0.3	-	0.3	-	tCK	
DQS, DQS rising edge output access time from rising CK, CK	tDQSCK	-300	300	-255	255	ps	13,f
DQS, DQS low-impedance time (Referenced from RL-1)	tLZ(DQS)	-600	300	-500	250	ps	13,14,f
DQS, DQS high-impedance time (Referenced from RL+BL/2)	tHZ(DQS)	-	300	-	250	ps	13,14, f
DQS, DQS differential input low pulse width	tDQSL	0.45	0.55	0.45	0.55	tCK(avg)	29, 31
DQS, DQS differential input high pulse width	tDQSH	0.45	0.55	0.45	0.55	tCK(avg)	30, 31
DQS, DQS rising edge to CK, CK rising edge	tDQSS	-0.25	0.25	-0.25	0.25	tCK(avg)	c
DQS, DQS falling edge setup time to CK, CK rising edge	tDSS	0.2	-	0.2	-	tCK(avg)	c, 32
DQS, DQS falling edge hold time to CK, CK rising edge	tDSH	0.2	-	0.2	-	tCK(avg)	c, 32

## Timing Parameters by Speed Bin (Cont.)

Speed		DDR3-1066		DDR3-1333		Units	Note
Parameter	Symbol	MIN	MAX	MIN	MAX		
<b>Command and Address Timing</b>							
DLL locking time	tDLLK	512	-	512	-	nCK	
internal READ Command to PRECHARGE Command delay	tRTP	max (4nCK,7.5ns)	-	max (4nCK,7.5ns)	-		e
Delay from start of internal write transaction to internal read command	tWTR	max (4nCK,7.5ns)	-	max (4nCK,7.5ns)	-		e,18
WRITE recovery time	tWR	15	-	15	-	ns	e, 18
Mode Register Set command cycle time	tMRD	4	-	4	-	nCK	
Mode Register Set command update delay	tMOD	max (12nCK,15ns)	-	max (12nCK,15ns)	-		
CAS# to CAS# command delay	tCCD	4	-	4	-	nCK	
Auto precharge write recovery + precharge time	tDAL(min)	WR + roundup (tRP / tCK(AVG))				nCK	
Multi-Purpose Register Recovery Time	tMPRR	1	-	1	-	nCK	22
ACTIVE to PRECHARGE command period	tRAS	See " Speed Bins and CL, tRCD, tRP, tRC and tRAS for corresponding Bin"				ns	e
ACTIVE to ACTIVE command period for 1KB page size	tRRD	max (4nCK,7.5ns)	-	max (4nCK,6ns)	-		e
ACTIVE to ACTIVE command period for 2KB page size	tRRD	max (4nCK,10ns)	-	max (4nCK,7.5ns)	-		e
Four activate window for 1KB page size	tFAW	37.5	-	30	-	ns	e
Four activate window for 2KB page size	tFAW	50	-	45	-	ns	e
Command and Address setup time to CK, $\overline{CK}$ referenced to $V_{IH}(AC) / V_{IL}(AC)$ levels	tIS(base)	125	-	65	-	ps	b,16
Command and Address hold time from CK, $\overline{CK}$ referenced to $V_{IH}(AC) / V_{IL}(AC)$ levels	tIH(base)	200	-	140	-	ps	b,16
Command and Address setup time to CK, $\overline{CK}$ referenced to $V_{IH}(AC) / V_{IL}(AC)$ levels	tIS(base) AC150	125 + 150	-	65+125	-	ps	b,16,27
Control & Address Input pulse width for each input	tIPW	780	-	620	-	ps	28
<b>Calibration Timing</b>							
Power-up and RESET calibration time	tZQinitl	512	-	512	-	nCK	
Normal operation Full calibration time	tZQoper	256	-	256	-	nCK	
Normal operation short calibration time	tZQCS	64	-	64	-	nCK	23
<b>Reset Timing</b>							
Exit Reset from CKE HIGH to a valid command	tXPR	max(5nCK, tRFC + 10ns)	-	max(5nCK, tRFC + 10ns)	-		
<b>Self Refresh Timing</b>							
Exit Self Refresh to commands not requiring a locked DLL	tXS	max(5nCK,tRFC + 10ns)	-	max(5nCK,tRFC + 10ns)	-		
Exit Self Refresh to commands requiring a locked DLL	tXSDLL	tDLLK(min)	-	tDLLK(min)	-	nCK	
Minimum CKE low width for Self refresh entry to exit timing	tCKESR	tCKE(min) + 1tCK	-	tCKE(min) + 1tCK	-		
Valid Clock Requirement after Self Refresh Entry (SRE) or Power-Down Entry (PDE)	tCKSRE	max(5nCK, 10ns)	-	max(5nCK, 10ns)	-		
Valid Clock Requirement before Self Refresh Exit (SRX) or Power-Down Exit (PDX) or Reset Exit	tCKSRX	max(5nCK, 10ns)	-	max(5nCK, 10ns)	-		

## Timing Parameters by Speed Bin (Cont.)

Speed		DDR3-1066		DDR3-1333		Units	Note
Parameter	Symbol	MIN	MAX	MIN	MAX		
<b>Power Down Timing</b>							
Exit Power Down with DLL on to any valid command; Exit Precharge Power Down with DLL frozen to commands not requiring a locked DLL	tXP	max (3nCK, 7.5ns)	-	max (3nCK, 6ns)	-		
Exit Precharge Power Down with DLL frozen to commands requiring a locked DLL	tXPDLL	max (10nCK, 24ns)	-	max (10nCK, 24ns)	-		2
CKE minimum pulse width	tCKE	max (3nCK, 5.625ns)	-	max (3nCK, 5.625ns)	-		
Command pass disable delay	tCPDED	1	-	1	-	nCK	
Power Down Entry to Exit Timing	tPD	tCKE(min)	9*tREFI	tCKE(min)	9*tREFI	tCK	15
Timing of ACT command to Power Down entry	tACTPDEN	1	-	1	-	nCK	20
Timing of PRE command to Power Down entry	tPRPDEN	1	-	1	-	nCK	20
Timing of RD/RDA command to Power Down entry	tRDPDEN	RL + 4 +1	-	RL + 4 +1	-		
Timing of WR command to Power Down entry (BL8OTF, BL8MRS, BL4OTF)	tWRPDEN	WL + 4 +(tWR/tCK(avg))	-	WL + 4 +(tWR/tCK(avg))	-	nCK	9
Timing of WRA command to Power Down entry (BL8OTF, BL8MRS, BL4OTF)	tWRAPDEN	WL + 4 +WR +1	-	WL + 4 +WR +1	-	nCK	10
Timing of WR command to Power Down entry (BL4MRS)	tWRPDEN	WL + 2 +(tWR/tCK(avg))	-	WL + 2 +(tWR/tCK(avg))	-	nCK	9
Timing of WRA command to Power Down entry (BL4MRS)	tWRAPDEN	WL +2 +WR +1	-	WL +2 +WR +1	-	nCK	10
Timing of REF command to Power Down entry	tREFPDEN	1	-	1	-		20,21
Timing of MRS command to Power Down entry	tMRSPDEN	tMOD(min)	-	tMOD(min)	-		
<b>ODT Timing</b>							
ODT high time without write command or with write command and BC4	ODTH4	4	-	4	-	nCK	
ODT high time with Write command and BL8	ODTH8	6	-	6	-	nCK	
Asynchronous RTT turn-on delay (Power-Down with DLL frozen)	tAONPD	2	8.5	2	8.5	ns	
Asynchronous RTT turn-off delay (Power-Down with DLL frozen)	tAOFPD	2	8.5	2	8.5	ns	
ODT turn-on	tAON	-300	300	-250	250	ps	7,f
RTT_NOM and RTT_WR turn-off time from ODTloff reference	tAOF	0.3	0.7	0.3	0.7	tCK(avg)	8,f
RTT dynamic change skew	tADC	0.3	0.7	0.3	0.7	tCK(avg)	f
<b>Write Leveling Timing</b>							
First DQS pulse rising edge after tDQSS margining mode is programmed	tWLMRD	40	-	40	-	tCK	3
DQS/DQS delay after tDQSS margining mode is programmed	tWLDQSEN	25	-	25	-	tCK	3
Setup time for tDQSS latch	tWLS	245	-	195	-	ps	
Write leveling hold time from rising DQS, $\overline{DQS}$ crossing to rising CK, $\overline{CK}$ crossing	tWLH	245	-	195	-	ps	
Write leveling output delay	tWLO	0	9	0	9	ns	
Write leveling output error	tWLOE	0	2	0	2	ns	

## 15.1 Jitter Notes

- Specific Note a** Unit 'tCK(avg)' represents the actual tCK(avg) of the input clock under operation. Unit 'nCK' represents one clock cycle of the input clock, counting the actual clock edges.  
ex) tMRD = 4 [nCK] means; if one Mode Register Set command is registered at Tm, another Mode Register Set command may be registered at Tm+4, even if (Tm+4 - Tm) is  $4 \times tCK(\text{avg}) + tERR(4\text{per}),\text{min}$ .
- Specific Note b** These parameters are measured from a command/address signal (CKE, CS, RAS, CAS, WE, ODT, BA0, A0, A1, etc.) transition edge to its respective clock signal (CK/CK) crossing. The spec values are not affected by the amount of clock jitter applied (i.e. tJIT(per), tJIT(cc), etc.), as the setup and hold are relative to the clock signal crossing that latches the command/address. That is, these parameters should be met whether clock jitter is present or not.
- Specific Note c** These parameters are measured from a data strobe signal (DQS(L/U), DQS(L/U)) crossing to its respective clock signal (CK, CK) crossing. The spec values are not affected by the amount of clock jitter applied (i.e. tJIT(per), tJIT(cc), etc.), as these are relative to the clock signal crossing. That is, these parameters should be met whether clock jitter is present or not.
- Specific Note d** These parameters are measured from a data signal (DM(L/U), DQ(L/U)0, DQ(L/U)1, etc.) transition edge to its respective data strobe signal (DQS(L/U), DQS(L/U)) crossing.
- Specific Note e** For these parameters, the DDR3 SDRAM device supports  $t_{PARAM} [nCK] = RU\{ t_{PARAM} [\text{ns}] / tCK(\text{avg}) [\text{ns}] \}$ , which is in clock cycles, assuming all input clock jitter specifications are satisfied. For example, the device will support  $t_{RP} = RU\{t_{RP} / tCK(\text{avg})\}$ , which is in clock cycles, if all input clock jitter specifications are met. This means: For DDR3-800 6-6-6, of which  $t_{RP} = 15\text{ns}$ , the device will support  $t_{RP} = RU\{t_{RP} / tCK(\text{avg})\} = 6$ , as long as the input clock jitter specifications are met, i.e. Precharge command at Tm and Active command at Tm+6 is valid even if  $(Tm+6 - Tm)$  is less than 15ns due to input clock jitter.
- Specific Note f** When the device is operated with input clock jitter, this parameter needs to be derated by the actual tERR(mper),act of the input clock, where  $2 \leq m \leq 12$ . (output deratings are relative to the SDRAM input clock.)  
For example, if the measured jitter into a DDR3-800 SDRAM has  $t_{ERR}(\text{mper}),act,\text{min} = -172\text{ ps}$  and  $t_{ERR}(\text{mper}),act,\text{max} = +193\text{ ps}$ , then  $t_{DQSCK,min}(\text{derated}) = t_{DQSCK,min} - t_{ERR}(\text{mper}),act,\text{max} = -400\text{ ps} - 193\text{ ps} = -593\text{ ps}$  and  $t_{DQSCK,max}(\text{derated}) = t_{DQSCK,max} - t_{ERR}(\text{mper}),act,\text{min} = 400\text{ ps} + 172\text{ ps} = +572\text{ ps}$ . Similarly,  $t_{LZ}(DQ)$  for DDR3-800 derates to  $t_{LZ}(DQ),min(\text{derated}) = -800\text{ ps} - 193\text{ ps} = -993\text{ ps}$  and  $t_{LZ}(DQ),max(\text{derated}) = 400\text{ ps} + 172\text{ ps} = +572\text{ ps}$ . (Caution on the min/max usage!) Note that  $t_{ERR}(\text{mper}),act,\text{min}$  is the minimum measured value of  $t_{ERR}(\text{nper})$  where  $2 \leq n \leq 12$ , and  $t_{ERR}(\text{mper}),act,\text{max}$  is the maximum measured value of  $t_{ERR}(\text{nper})$  where  $2 \leq n \leq 12$ .
- Specific Note g** When the device is operated with input clock jitter, this parameter needs to be derated by the actual tJIT(per),act of the input clock. (output deratings are relative to the SDRAM input clock.) For example, if the measured jitter into a DDR3-800 SDRAM has  $t_{CK}(\text{avg}),act = 2500\text{ ps}$ ,  $t_{JIT}(\text{per}),act,\text{min} = -72\text{ ps}$  and  $t_{JIT}(\text{per}),act,\text{max} = +93\text{ ps}$ , then  $t_{RP},min(\text{derated}) = t_{RP},min + t_{JIT}(\text{per}),act,\text{min} = 0.9 \times t_{CK}(\text{avg}),act + t_{JIT}(\text{per}),act,\text{min} = 0.9 \times 2500\text{ ps} - 72\text{ ps} = +2178\text{ ps}$ . Similarly,  $t_{QH},min(\text{derated}) = t_{QH},min + t_{JIT}(\text{per}),act,\text{min} = 0.38 \times t_{CK}(\text{avg}),act + t_{JIT}(\text{per}),act,\text{min} = 0.38 \times 2500\text{ ps} - 72\text{ ps} = +878\text{ ps}$ . (Caution on the min/max usage!)

## 15.2 Timing Parameter Notes

1. Actual value dependant upon measurement level definitions which are TBD.
2. Commands requiring a locked DLL are: READ (and RAP) and synchronous ODT commands.
3. The max values are system dependent.
4. WR as programmed in mode register
5. Value must be rounded-up to next higher integer value
6. There is no maximum cycle time limit besides the need to satisfy the refresh interval, tREFI.
7. For definition of RTT turn-on time tAON see "Device Operation & Timing Diagram Datasheet"
8. For definition of RTT turn-off time tAOF see "Device Operation & Timing Diagram Datasheet".
9. tWR is defined in ns, for calculation of tWRPDEN it is necessary to round up tWR / tCK to the next integer.
10. WR in clock cycles as programmed in MR0
11. The maximum read postamble is bound by tDQSK(min) plus tQSH(min) on the left side and tHZ(DQS)max on the right side. Device Operation.
12. Output timing deratings are relative to the SDRAM input clock. When the device is operated with input clock jitter, this parameter needs to be derated by TBD
13. Value is only valid for RON34
14. Single ended signal parameter.
15. tREFI depends on  $T_{OPER}$
16. tIS(base) and tIH(base) values are for 1V/ns CMD/ADD single-ended slew rate and 2V/ns CK,  $\overline{CK}$  differential slew rate, Note for DQ and DM signals,  $V_{REF}(DC) = V_{REF}DQ(DC)$ . For input only pins except RESET,  $V_{REF}(DC) = V_{REF}CA(DC)$ . See "Address/ Command Setup, Hold and Derating"
17. tDS(base) and tDH(base) values are for 1V/ns DQ single-ended slew rate and 2V/ns DQS,  $\overline{DQS}$  differential slew rate. Note for DQ and DM signals,  $V_{REF}(DC) = V_{REF}DQ(DC)$ . For input only pins except RESET,  $V_{REF}(DC) = V_{REF}CA(DC)$ . See "Data Setup, Hold and Slew Rate Derating"
18. Start of internal write transaction is defined as follows :  
For BL8 (fixed by MRS and on-the-fly) : Rising clock edge 4 clock cycles after WL.  
For BC4 (on-the-fly) : Rising clock edge 4 clock cycles after WL  
For BC4 (fixed by MRS) : Rising clock edge 2 clock cycles after WL
19. The maximum read preamble is bound by tLZDQS(min) on the left side and tDQSK(max) on the right side. See "Device Operation"
20. CKE is allowed to be registered low while operations such as row activation, precharge, autoprecharge or refresh are in progress, but power-down IDD spec will not be applied until finishing those operations.
21. Although CKE is allowed to be registered LOW after a REFRESH command once tREFPDEN(min) is satisfied, there are cases where additional time such as tXPDL(min) is also required. See "Device Operation".
22. Defined between end of MPR read burst and MRS which reloads MPR or disables MPR function.
23. One ZQCS command can effectively correct a minimum of 0.5 % (ZQCorrection) of RON and RTT impedance error within 64 nCK for all speed bins assuming the maximum sensitivities specified in the 'Output Driver Voltage and Temperature Sensitivity' and 'ODT Voltage and Temperature Sensitivity' tables. The appropriate interval between ZQCS commands can be determined from these tables and other application specific parameters.  
One method for calculating the interval between ZQCS commands, given the temperature (Tdriffrate) and voltage (Vdriffrate) drift rates that the SDRAM is subject to in the application, is illustrated. The interval could be defined by the following formula:

$$\text{ZQCorrection} \\ \frac{0.5}{(TSens \times Tdriffrate) + (VSens \times Vdriffrate)}$$

where TSens =  $\max(dRTTdT, dRONdTM)$  and VSens =  $\max(dRTTdV, dRONdVM)$  define the SDRAM temperature and voltage sensitivities.

For example, if TSens = 1.5% /°C, VSens = 0.15% / mV, Tdriffrate = 1°C / sec and Vdriffrate = 15 mV / sec, then the interval between ZQCS commands is calculated as:

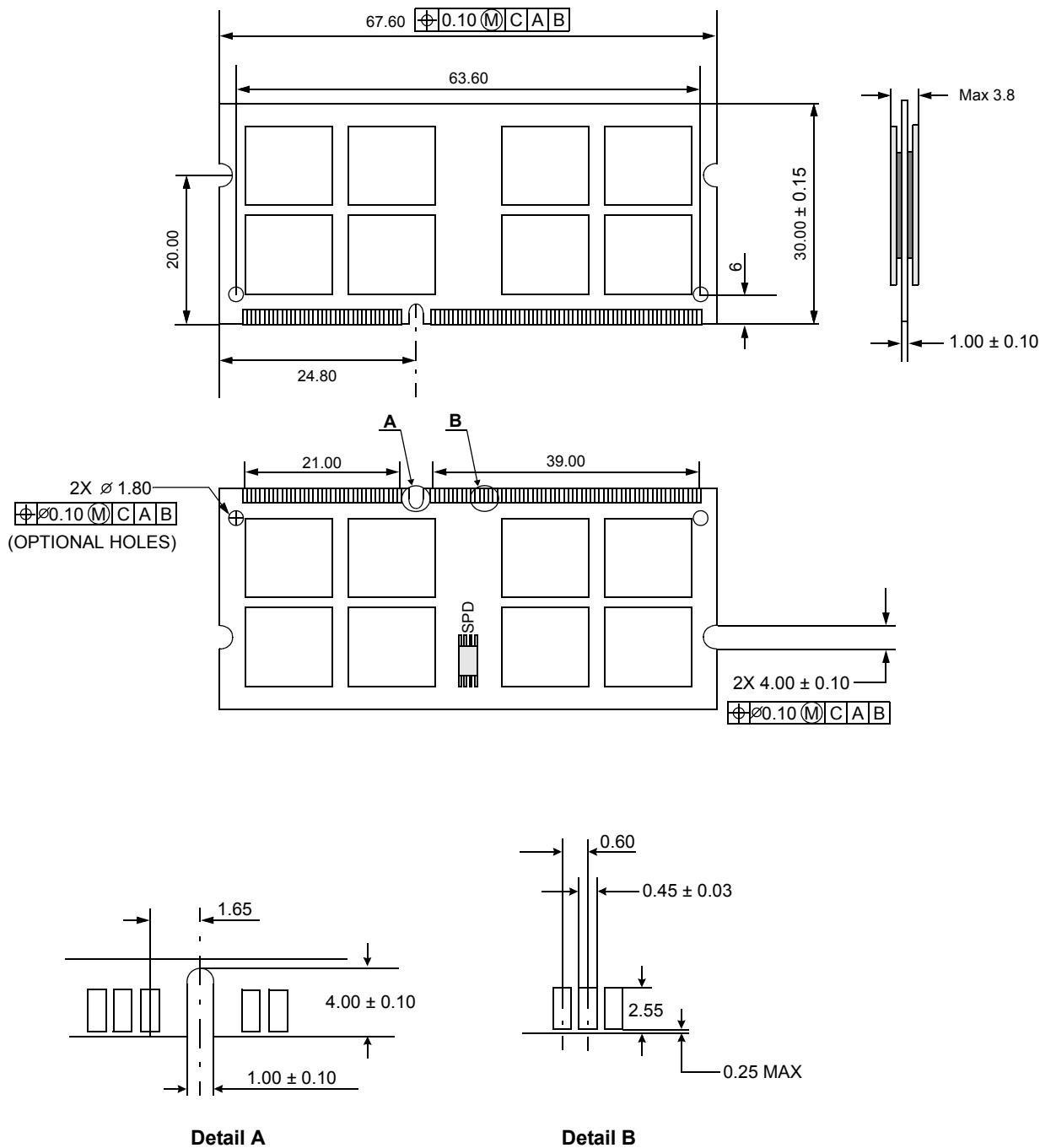
$$\frac{0.5}{(1.5 \times 1) + (0.15 \times 15)} = 0.133 \approx 128\text{ms}$$

24. n = from 13 cycles to 50 cycles. This row defines 38 parameters.
25. tCH(abs) is the absolute instantaneous clock high pulse width, as measured from one rising edge to the following falling edge.
26. tCL(abs) is the absolute instantaneous clock low pulse width, as measured from one falling edge to the following rising edge.
27. The tIS(base) AC150 specifications are adjusted from the tIS(base) specification by adding an additional 100 ps of derating to accommodate for the lower alternate threshold of 150 mV and another 25 ps to account for the earlier reference point [(175 mV - 150 mV) / 1 V/ns].
28. Pulse width of a input signal is defined as the width between the first crossing of  $V_{REF}(DC)$  and the consecutive crossing of  $V_{REF}(DC)$
29. tDQSL describes the instantaneous differential input low pulse width on DQS- $\overline{DQS}$ , as measured from one falling edge to the next consecutive rising edge.
30. tDQSH describes the instantaneous differential input high pulse width on DQS- $\overline{DQS}$ , as measured from one rising edge to the next consecutive falling edge.
31. tDQSH, act + tDQSL, act = 1 tCK, act ; with tXYZ, act being the actual measured value of the respective timing parameter in the application.
32. tDSS, act + tDSS, act = 1 tCK, act ; with tXYZ, act being the actual measured value of the respective timing parameter in the application.

## 16.0 Physical Dimensions :

16.1 256Mb<sup>x</sup>8 based 512Mx64 Module (2 Ranks)

Units : Millimeters



The used device is 256M x8 DDR3 SDRAM, FBGA.  
DDR3 SDRAM Part NO : K4B2G0846B - HC\*\*